The geometry of random graphs with a Markov flavour

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I. Random graphs

2. Encoding dependence

3. The stability of ERGMs



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Random graphs

What are random graphs?

a set of graphs + some (measurable) uncertainty

a set of graphs + a probability distribution

Random subgraphs of K_m

- A random subset $S \subseteq E := E(K_m)$: a random variable that assigns a probability to each subset of edges
- Equivalently, if $E = [n] = \{1, 2, \dots, n\}$, then a random subset $S \subseteq E$ is a random element of $\mathcal{P}([n])$

Generating polynomials

• Well-developed ([BBL09], [ALGV19]) dictionary

 $\{\text{probability distributions}\} \longleftrightarrow \{\text{multivariate polynomials}\}$

• def. For X a random subgraph, its generating polynomial is

$$F_X := \sum_{S \subseteq E} P(X = S) \mathbf{x}^S$$

where $\mathbf{x}^S = \prod_{i \in S} x_i$ and $\mathbf{x} = (x_1, \dots, x_n)$

 def. A nonzero polynomial F ∈ ℝ[x₁, x₂,..., x_n] is (real) stable if it does not have any roots in the open upper half of the complex plane H = {z ∈ ℂ : lm(z) > 0}.



When is F_X stable?

The first ideas and strides: Erdős-Rényi

- Erdős-Rényi graphs G(m,p) for $m \in \mathbb{N}, 0$
 - I. Start with m vertices



- 2. Draw an edge between each pair of vertices with independent probability p
- The giant component for $mp \rightarrow c > 1$
 - ▷ All other components will contain at most $O(\log m)$ vertices
- · Limitations: modelling complex systems
 - Independence is uncommon in networks

Erdős-Rényi graphs

• For
$$S \subseteq E$$
, $P(X = S) = p^{|S|}(1 - p)^{n - |S|}$

Proposition

If X is Erdős-Rényi, then $F_X = \prod_{e \in [n]} (px_e + (1 - p))$ and this is a stable polynomial.



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- Each edge in the Erdős-Rényi model is independent of the rest
- Markov assumption: Adjacent edges are dependent



• def. A neighbourhood clique is a subset of pairwise dependent edges.

Markov random graphs

• def. The Markov random graph model on $\mathcal{P}([n])$ is:

$$P(X = G) \propto \exp\left(at_3(G) + \sum_{k < m} b_k s_k(G)\right)$$



Hammersley-Clifford theorem [Bré20]

Markov random graphs

Proposition

If n = 3 and a = 0, then F_X is stable for any $b_1, b_2 \in \mathbb{R}$.

Proposition

If n = 4, then the stability of F_X does not depend on the edge and 2-star parameters b_1 and b_2 .

Exponential random graphs (ERGMs)

- We can define a more general model with the following parameters:
 - \triangleright T > 0: temperature parameter
 - \triangleright F : a finite set of test graphs H
 - ▷ $\{a_H\}_{H \in F} \in \mathbb{R}^F$: a real parameter for each test graph
- def. $n_H(G) := \# \operatorname{lnj}(H, G) = \# \{ H \hookrightarrow G \}$
- def. The exponential random graph model (ERGM) with the above parameters is

$$P(X = G_T) \propto \exp\left(\frac{1}{T}\sum_{H \in F} a_H n_H(G)\right)$$



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Behaviour with respect to temperature

Variational Question I

Fix $\{a_H\}_{H \in F}$. For which T is F_{G_T} stable?

Variational Question 2

Fix T. For which parameters $\{a_H\}_{H \in F}$ is F_{G_T} stable?

Variational Question I

Theorem I

Let X be an ERGM. If $a_H > 0$ for all $H \in F$ and T > 0 is sufficiently large, then F_{G_T} is stable.

• What about other parameter values and their relationship to the temperature threshold?

Variational Question 2

Theorem 2

Let X be a Markov ERGM and fix T > 0. Then, F_G is stable for one b_2 iff it is stable for all b_2 .

Proof sketch:

- Replace subgraph counts with homomorphism counts [Lov12]
- hom $(S_k, G) = \sum_{i \in V(G)} \deg(i)^{k-1}$
- $\hom(S_2, G) = 2|E(G)|$
- Specialize to a univariate polynomial [BBL09]
- Apply the Hermite-Sylvester theorem [Nat19]: a univariate polynomial is real-rooted iff its Hermite matrix is positive semidefinite

Thank you!

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